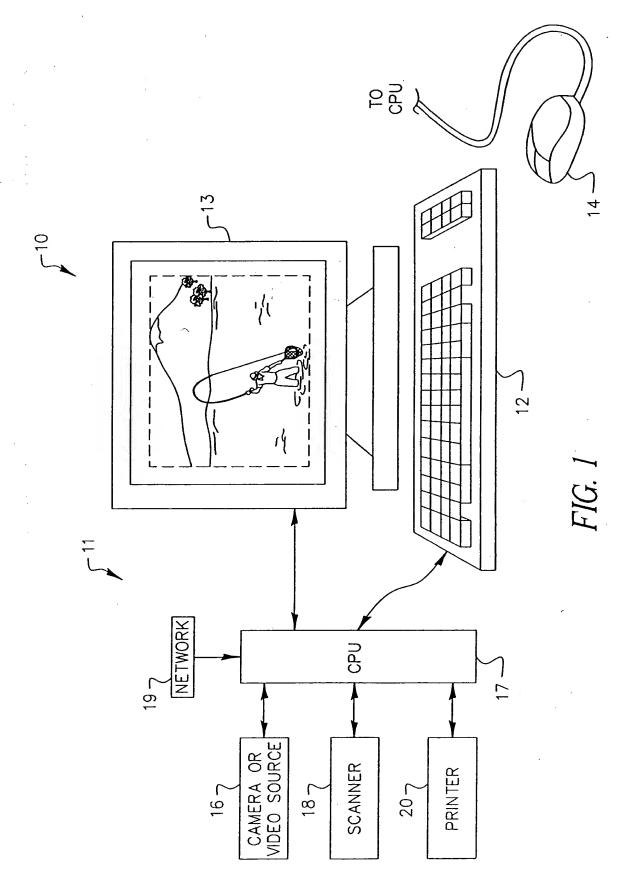
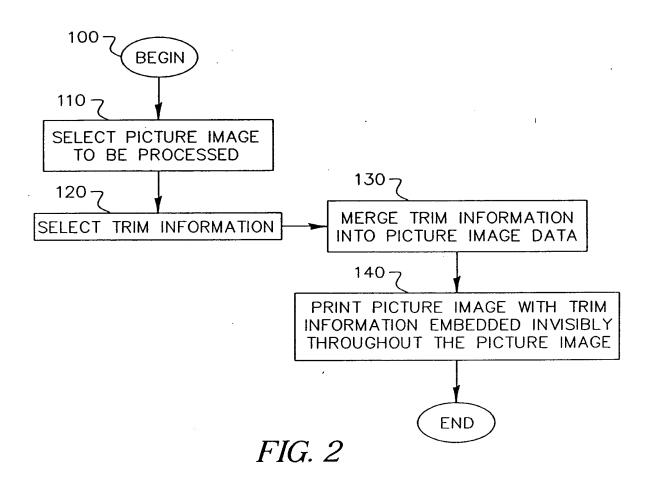


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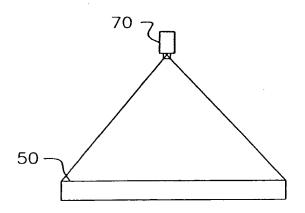
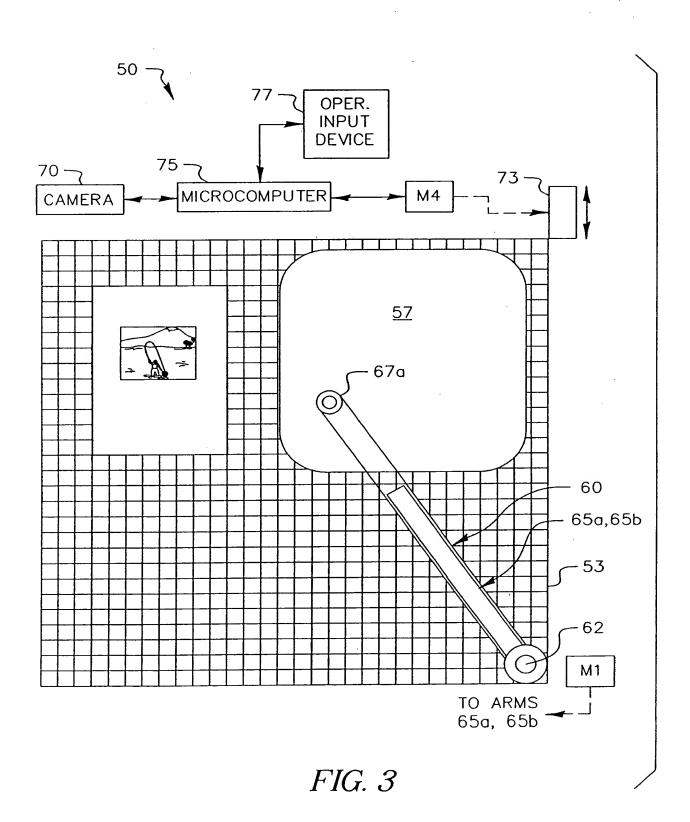


FIG. 4



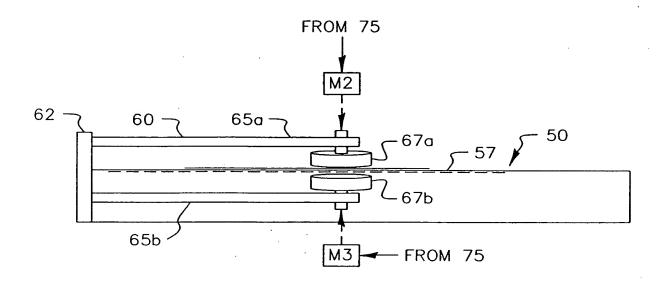


FIG. 5

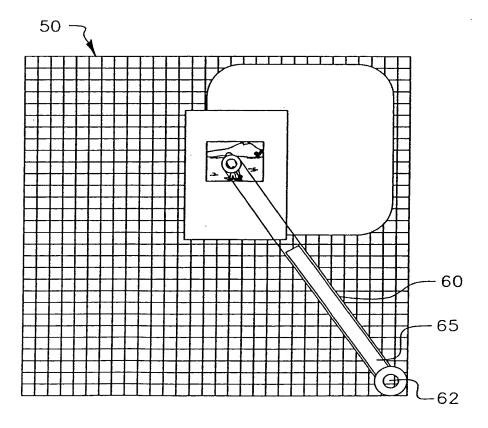
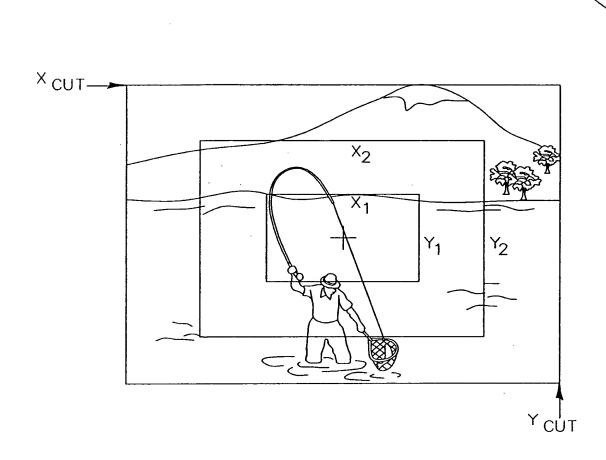


FIG. 6



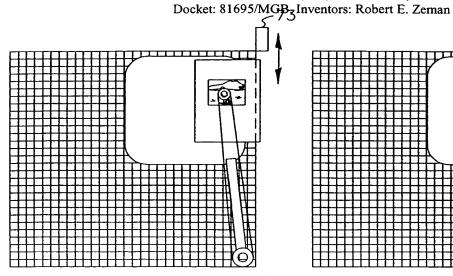
ALGORITHM APPLIED: 
$$X_{CUT} = X_1 + X_2$$

$$Y_{CUT} = Y_1 + Y_2$$

CENTERED ON THE CROSSHAIRS

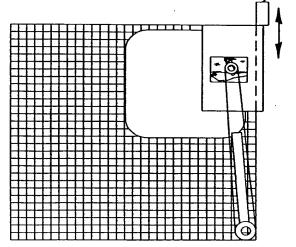
FIG. 7

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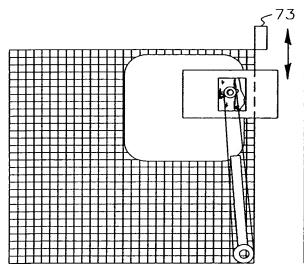
HEAD TRANSLATION & ROTATION TO FIRST EDGE CUT

FIG. 8a



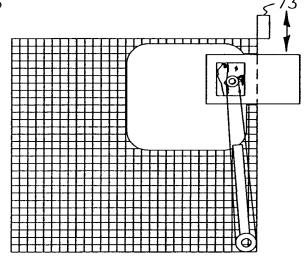
180 DEG. ROTATION TO SECOND EDGE CUT

FIG. 8b



HEAD TRANSLATION AND 90 DEG. ROTATION TO THIRD EDGE CUT

FIG. 8c



180 DEG. ROTATION TO LAST EDGE CUT

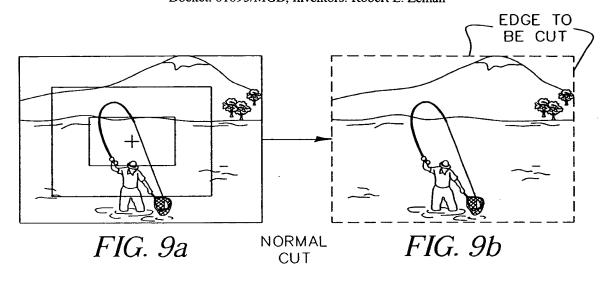
FIG. 8d

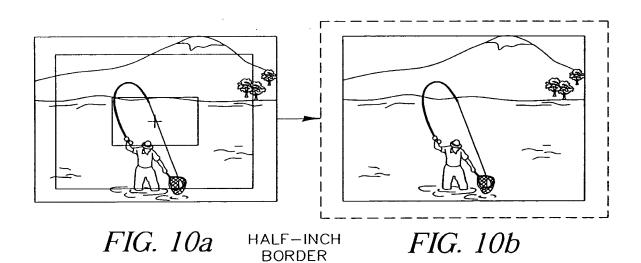


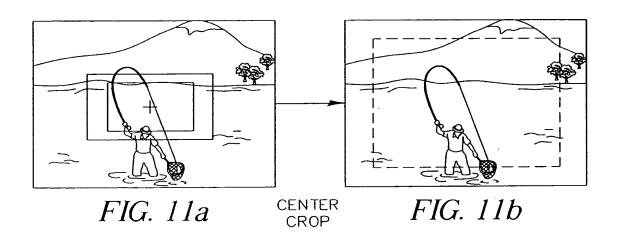
FINISHED CUT FIG. 8e

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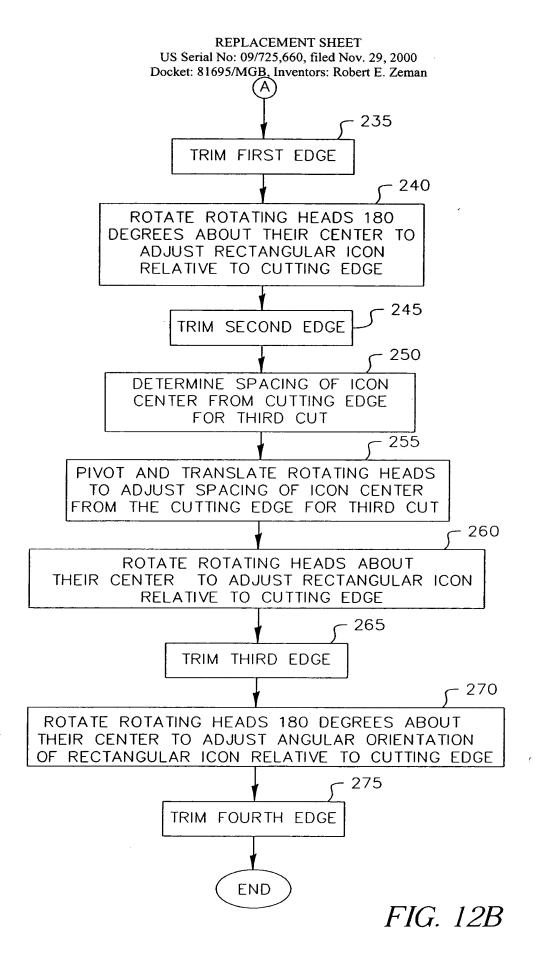


CUT

#### REPLACEMENT SHEET

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**BEGIN** FIG. - 205 12A CAMERA SENSOR VIEWS CUTTING BOARD AREA - 210 FIG. PROCESS PICTURE 12B INFORMATION - 213 FIG. 12 IDENTIFY ROWS AND COLUMNS OF ICON INFORMATION FROM CODE IN PICTURE - 215 DETERMINE ICON'S CENTER IN REAL DIMENSIONS - 217 MOVE ROTATIONG HEADS TO ICON CENTER AND CLAMP ON PICTURE 220 DETERMINE SPACING OF ICON CENTER FROM CUTTING EDGE FOR FIRST CUT - 225 PIVOT AND TRANSLATE ROTATING HEADS TO POSITION ICON CENTER AT CORRECT SPACING FROM CUTTING EDGE FOR FIRST CUT - 230 ROTATE ROTATING HEADS ABOUT THEIR CENTER TO ADJUST ANGULAR ORIENTATION OF RECTANGULAR ICON RELATIVE TO CUTTING EDGE FIG. 12A



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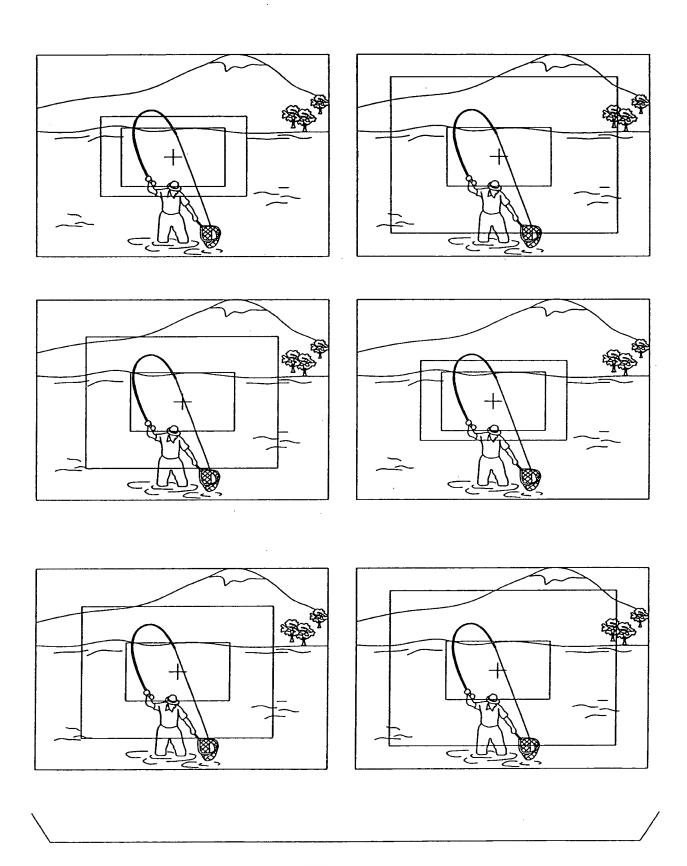


FIG. 13

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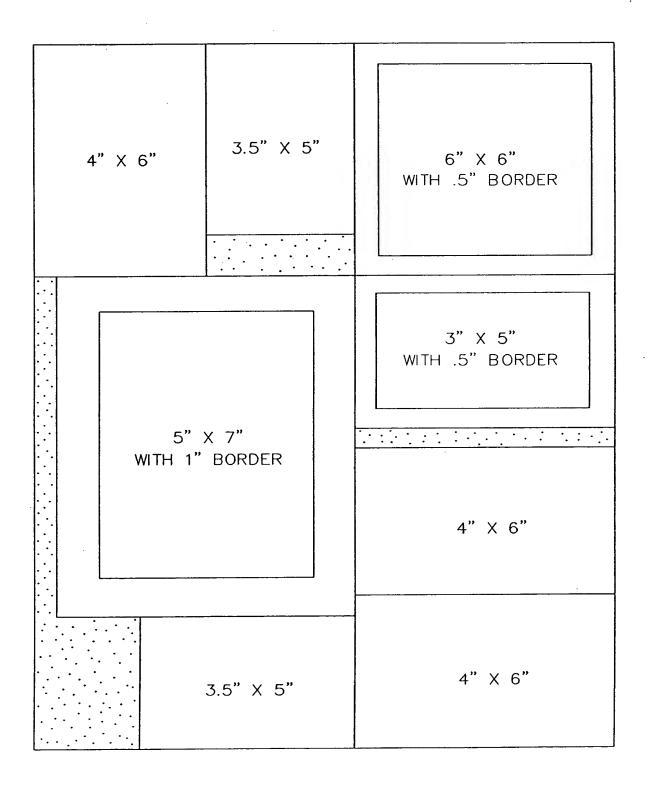


FIG. 14

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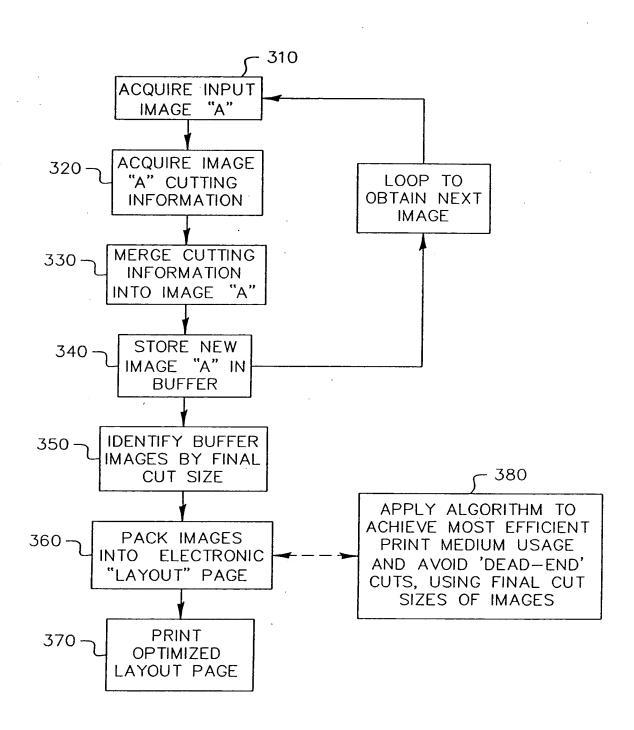


FIG. 15

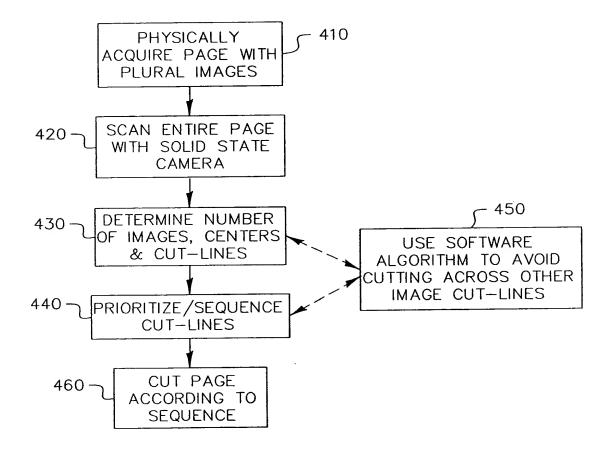


FIG. 16